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1. About this document

Wiring examples

1.1 Function

This operating instructions manual provides all the information you need for the mounting, set-up and commissioning to ensure the safe operation and disassembly of the safety-monitoring module. the operating instructions must be available in a legible condition and a complete version in the vicinity of the device.

1.2 Target group: authorised qualified personnel

All operations described in this operating instructions manual must be carried out by trained specialist personnel, authorised by the plant operator only.

Please make sure that you have read and understood these operating instructions and that you know all applicable legislations regarding occupational safety and accident prevention prior to installation and putting the component into operation.

The machine builder must carefully select the harmonised standards to be complied with as well as other technical specifications for the selection, mounting and integration of the components.

1.3 Explanation of the symbols used



Information, hint, note:

This symbol is used for identifying useful additional information.



Caution: Failure to comply with this warning notice could lead to failures or malfunctions.

Warning: Failure to comply with this warning notice could lead to physical injury and/or damage to the machine.

Operating instructions Fail-safe delay timer / Standstill monitor

1.4 Appropriate use

The products described in these operating instructions are developed to execute safety-related functions as part of an entire plant or machine. It is the responsibility of the manufacturer of a machine or plant to ensure the correct functionality of the entire machine or plant.

The fail-safe delay timer must be exclusively used in accordance with the versions listed below or for the applications authorised by the manufacturer. Detailed information regarding the range of applications can be found in the chapter "Product description".

1.5 General safety instructions

The user must observe the safety instructions in this operating instructions manual, the country specific installation standards as well as all prevailing safety regulations and accident prevention rules.



Further technical information can be found in the Schmersal catalogues or in the online catalogue on the Internet: www.schmersal.net.

The information contained in this operating instructions manual is provided without liability and is subject to technical modifications.

There are no residual risks, provided that the safety instructions as well as the instructions regarding mounting, commissioning, operation and maintenance are observed.

1.6 Warning about misuse



In case of inadequate or improper use or manipulations of the fail-safe delay timer, personal hazards or damage to machinery or plant components cannot be excluded. The relevant requirements of the standards ISO 14119 and ISO 13850 must be observed.

1.7 Exclusion of liability

We shall accept no liability for damages and malfunctions resulting from defective mounting or failure to comply with this operating instructions manual. The manufacturer shall accept no liability for damages resulting from the use of unauthorised spare parts or accessories.

For safety reasons, invasive work on the device as well as arbitrary repairs, conversions and modifications to the device are strictly forbidden; the manufacturer shall accept no liability for damages resulting from such invasive work, arbitrary repairs, conversions and/or modifications to the device.

The safety relay module is to be operated in an area in which access by personnel is restricted.

2. Product description

2.1 Ordering code

This operating instructions manual applies to the following types:

SRB-E-402FWS-TS-①

No.	Option	Description
1	cc	Plug-in screw clamps: single wire (rigid) or fine wire (flexible): 0.2 2.5 mm²; fine wire with ferrule: 0.25 2.5 mm² Plug-in cage clamps: single wire (rigid) or fine wire (flexible): 0.2 1.5 mm²; fine wire with ferrule: 0.25 1.5 mm²



Only if the action described in these operating instructions is carried out correctly will the safety function be safeguarded, including compliance with the Machinery Directive.

2.2 Special versions

For special versions, which are not listed in the order code below 2.1, these specifications apply accordingly, provided that they correspond to the standard version.

2.3 Purpose

Safe pull-in delay function

The fail-safe delay timers for integration in safety circuits are designed for fitting in control cabinets. They serve as a reliable means of evaluating actuation signals and delayed authorisation of protective equipment.

The safety function is defined as deactivation of the fail-safe outputs Q1 and Q2 when inputs S12 and/or S22 are opened and the fail-safe outputs are activated when the set activation delay time has elapsed.

Safe standstill monitoring function

The fail-safe standstill monitor is designed for control cabinet mounting. Standstill monitors serve for the fail-safe detection of the machine standstill and control of solenoid interlocks. If the safety control module has detected standstill, a solenoid interlock can be operated using the fail-safe outputs Q1 and Q2.

The signals from one or two proximity switches are used to detect standstill. Optionally, an additional standstill signal can be monitored. The additional standstill signal can be derived from an already available standstill signal of the machine, e.g. evaluation of a tachogenerator by a PLC or the standstill output of a frequency converter.

Protective equipment function

The safety relay modules for use in safety circuit are used for the safe evaluation of the signals from solenoid interlocks, positive break position switches or safety sensors on sliding, hinged and removable protective equipment, emergency stop control devices, safety solenoid switches and AOPDs.

The safety function is defined as deactivating outputs 13/14, 23/24 when inputs S32 and/or S42 are opened.

Taking account of a PFH value assessment, the safety-relevant current paths meet the following requirements (see also chapter 2.6 "Safety classification")

- Control category 4 PL e to ISO 13849-1
- SIL 3 to IEC 61508
- SILCL 3 to IEC 62061

max. 2,000 m

To determine the Performance Level (PL) to ISO 13849-1 of the entire safety function (e.g. sensor, logic, actuator), an assessment of all relevant components is required.



The entire concept of the control system, in which the safety component is integrated, must be validated to the relevant standards.

2.4 Technical data

General data	
Standards:	EN 60204-1, IEC 60947-5-1; ISO 13849-1,
	IEC 62061, IEC 61508
EMC rating:	to EMC Directive
Air clearances and creepage	e distances: to IEC 60664-1
Mounting:	standard DIN rail to EN 60715
Terminal designations:	IEC 60947-1
Electrical characteristics:	
Rated operating voltage U _e :	24 VDC -20%/+20%,
	residual ripple max. 10%
Frequency range:	-
Mains unit/mains power sup	ply: SELV network as per EN 60950;
	mains power supply must harmonise
	with device safety (characteristic/melting
	property) so that triggering is assured.
Power consumption:	3 W (+ load of the safety outputs)
Fuse rating for the operating	voltage: we recommend a circuit
	breaker type Z (max. 16 A) or a fine
	fuse (max. 15 A, delayed action)
UL Rating of external fuse:	max. 16 A, only use fuses in
	accordance with UL 248 series

Rated insulation voltage U _i :
- Safety contacts:
- Safety outputs:
Rated impulse withstand voltage U _{imp} :
- Safety contacts 13/14, 23/24:
- Safety output Q1/Q2:
Overvoltage category:

Insulation values to IEC 60664-1:

Drop-out delay on "supply failure"

Bridging in case of voltage drops:	typ. 5 ms
Readiness after switching on voltage [s]:	< 1.5 sec.
Frequency measurement tolerance:	< 2%
Time measurement tolerance:	2% + 30ms
Control current circuits/inputs:	
Inputs S12, S22, S32, S42:	24 VDC / 8 mA
Max. input frequency:	6000 Hz
Inputs X2, X3, X4, X5, X7:	24 VDC / 8 mA

Clock outputs S11, S21, S31, S41:	> 20 VDC, 10 mA per output
Cable length:	1500 m with 1.5 mm ² :
	2500 m with 2.5 mm ²
Conduction resistance:	max. 40 Ω

Jonadollon registarioe.	mux. +
Polav outnute:	

Relay outputs:	:
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Degree of pollution:

Switching capacity of the safety contacts:	13/14, 23/24:
	max. 250 V, 6 A ohmic,
	min. 10 VDC / 10 mA
	(Derating see 2.5)
Fuse rating of the safety contacts:	external (I _k = 1000 A)

to EN 60947-5-1

Safety fuse 10	A quick blow, 6 A slow blow
Utilisation category to IEC 60947-5-1:	AC-15: 230 V / 4 A
	DC-13: 24 V / 4 A
Cuitabing conscitu of the cuvilians contactes	44 42: 24 VDC / 4

Switching capacity of the auxiliary contacts:	41-42: 24 VDC / 1
	Α
Fuse rating for the auxiliary contact:	safety fuse

	2.5 A quick blow, 2 A slow blow
Electrical life:	refer to 2.5
Mechanical life:	10 million operations

Sem	i-cond	luctor	outpu	ts:

Switching capacity of the safety outputs:	Q1/Q2: max. 2 A
Voltage drop:	< 0.5 V
Leakage current:	< 1 mA
Max. fuse rating of the safety outputs:	refer to "Operating voltage"
Test impulse of the safety outputs:	< 1 ms (negative),
	< 100 µs (positive)
Utilisation category to IEC 60947-5-1:	DC-13: 24 V / 2A
Switching capacity of signaling outputs:	semi-conductor outputs Y1:
	24 VDC/100 mA
Fuse rating of the signalling outputs:	internal electronic trip,
	tripping current > 100 mA
Electrical life:	(Derating refer to 2.5)
Max. switching cycles / minute:	20
Inductive consumers: provi	sion is to be made for suitable
pr	otective wiring for suppression
Machanical data:	

Mechanical data:

250 V 50 V

6 kV 0.8 kV

< 10 ms

Ш

Altitude:

Connection type:	refer to 2.1
Cable section:	refer to 2.1
Connecting cable:	rigid or flexible
Tightening torque for the terminals:	0.5 Nm
Material of enclosure:	glass-fibre reinforced
	thermoplastic, ventilated
Weight:	180 g
Ambient conditions:	
Ambient temperature:	−25°C +60°C
	(non condensing)

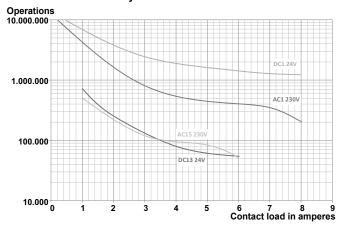
Weight:	180 g
Ambient conditions:	
Ambient temperature:	−25°C +60°C
	(non condensing)
Storage and transport temperature:	−40°C +85°C
	(non condensing)
Protection class:	Enclosure: IP40,
	Terminals: IP20,
	Clearance: IP54
Resistance to shock:	30 g / 11 ms
Resistance to vibrations	
to EN 60068-2-6:	10 55 Hz, amplitude 0.35 mm

2.5 Derating / electrical lifespan of safety contacts

No derating with individual installation of modules.

Derating on request if several modules are installed one after the other without spacing and with maximum output load and ambient temperatures.

Electrical life of the safety contacts



2.6 Safety classification

2.6.1 Safety classification of semi-conductor output

Standards:	ISO 13849-1, IEC 61508, IEC 62061
PL:	е
Control Category:	4
PFH _D :	≤ 2.66 x 10 ⁻⁹ / h
PFD _{avg} :	≤ 2.42 x 10 ⁻⁵
SIL:	suitable for SIL 3 applications
Service life:	20 years

2.6.2 Classification of relay output

Standards:	ISO 13849-1, IEC 61508, IEC 62061			
PL:	е			
Control Category:	4			
DC:	high			
CCF:	> 65 points			
PFH _D :	≤ 1.25 x 10 ⁻⁸ / h			
PFD _{avg} :	≤ 5.3 x 10 ⁻⁵			
SIL:	suitable for SIL 3 applications			
Service life:	20 years			

The PFH value of 1.25 × 10⁻⁸/h applies to the combinations of contact load (current through enabling contacts) and number of switching cycles (n_{opty}) mentioned in the table below. At 365 operating days per year and a 24-hours operation, this results in the below-mentioned switching cycle times (t_{cycle}) for the relay contacts. Diverging applications upon request.

n _{op/y}	t _{cycle}
880,000	0.6 min
330,000	1.6 min
110,000	5.0 min
44,000	12.0 min
17,600	30.0 min
	880,000 330,000 110,000 44,000

3. Mounting

3.1 General mounting instructions

Mounting: snaps onto standard DIN rails to EN 60715.

Hook bottom of enclosure in DIN rail and push down until it engages in position.



To avoid EMC disturbances, the physical ambient and operational conditions at the place where the product is installed, must meet the provisions laid down in the paragraph "Electromagnetic Compatibility (EMC)" of EN 60204-1.

Avoid laying proximity switch connection cables in areas where strong interference signals are present (e.g. frequency converters or cable leads from powerful electric motors); the utilisation of shielded cables may be necessary.



Mount proximity switches / pulse generators mechanically separated from each other (not on the same mounting angle). The toothed wheel (encoder) must be mounted on the shaft with a positive joint free of slip.

3.2 Dimensions

All measurements in mm.

Device dimensions (H/W/D): 98 x 22.5 x 115 mm

4. Rear side Electrical connection

4.1 General information for electrical connection

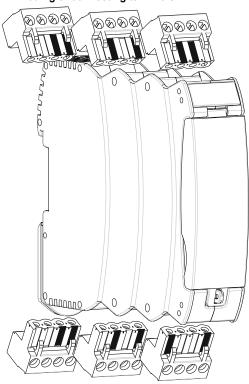


The electrical connection may only be carried out by authorised personnel in a de-energised condition.



If mains unit is a new installation or a replacement, the connector of the output level must be removed and correct connection of the power supply (A1) must be checked.

4.2 Coding of connecting terminals

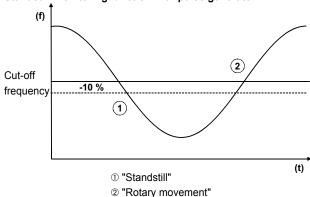


5. Operating principle and settings

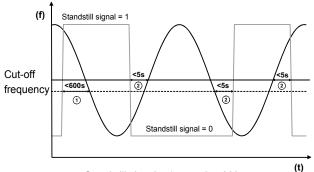
5.1 Description of the terminals and LED indications

Pin	Function	LED	Function
A1	Operating voltage + 24 VDC	RUN	Operating voltage OK RUN mode flash code, see section 5.3
A2	Operating voltage 0 V		
		ERR	Error code
			refer to part 6
X2	Reset input		
Х3	Start input Q1/Q2		
X4	Start guard system		
X5	Feedbackloop		
X7	Input additional standstill signal		
S11/S21 S31/S41	Test pulse outputs		
S12 S22	Input channel 1 Input channel 2	In1/2	High level at S12/S22 flash code, see section 6
S32	Input channel 1	In3/4	High level at S32/S42
S42	Input channel 2		flash code, see section 6
Y1	Diagnostic output Error code		flash code, see section 6
41/42	Signalling contact (NC)		
Q1/Q2	Safety outputs	Out 1	Outputs activated
	(standstill / time)		flash code, see section 6
13/14	Safety contacts	Out 2	Outputs activated
23/34	Guard system		flash code, see section 6

Standstill monitoring function with pulse generator



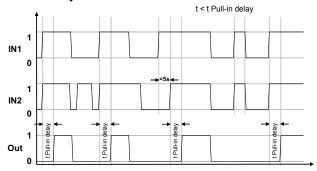
Standstill monitoring function with pulse generator and standstill signal

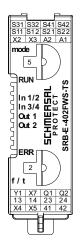


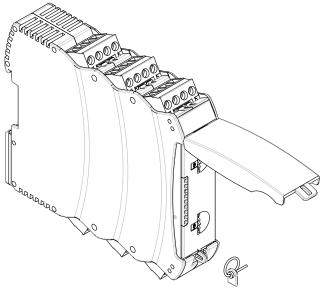
① Standstill signal = 1, max. lag 600s

 $\hbox{@ Difference monitoring max. 5s permitted}\\$

Fail-safe delay timer function







Adjustment of application using rotary "mode" switch

- · Open front transparent cover (see fig.).
- · Opening is carried out by lifting side with lock.
- Select desired application using rotary mode switch (1 ... 15) by turning up or down (see 5.3).
- Set pull-in delay or cut-off frequency by turning the f/t rotary switch up or down (see 5.3).
- After performing setting, close front cover again.
- The front cover can be secured with a seal for protection against unintentional opening



Only touch the components after electrical discharge!

5.2 Adjustable applications

Adjustable applications standstill monitoring / safety guard monitoring:

	Rotary switch (mode)				Rotary knob f / t	
	Safety g	uard monitoring con	figuration	FWS		
Pos.	Start / Reset monitoring	Cross-wire monitoring	Contact con- figuration (without synchronism)	Configuration timebase	Pos.	Cut-off frequency (Hz)
1	Yes	Yes	NC / NC	2 sensors	1	0.5
2	Yes	No	NC / NC	2 sensors	2	1
3	Autostart	Yes	NC / NC	2 sensors	3	2
4	Autostart	No	NC / NC	2 sensors	4	3
5	Yes	Yes	NC / NC	Sensor + standstill signal	5	4
6	Yes	No	NC / NC	Sensor + standstill signal	6	5
7	Autostart	No	NC / NC	Sensor + standstill signal	7	8
С		Co	onfiguration mode		8	10

Adjustable applications delay timer / safety guard monitoring:

		Rotary switch	n (mode)			Rotary knol	of/t	
	Safety guard monitoring configuration			TS		Pull-in delay (s)		
Pos.	Start / Reset monitoring	Cross-wire monitoring	Contact con- figuration (without synchronism)	Configuration timebase	Pos.	Time 1	Time 2	
8	Yes	Yes	NC / NC	Time 1	1	0.5	50	
9	Yes	No	NC / NC	Time 1	2	1	60	
10	Autostart	Yes	NC / NC	Time 1	3	1.5	70	
11	Autostart	No	NC / NC	Time 1	4	2	80	
12	Yes	Yes	NC / NC	Time 2	5	2.5	100	
13	Yes	No	NC / NC	Time 2	6	3	120	
14	Autostart	Yes	NC / NC	Time 2	7	4	150	
15	Autostart	No	NC / NC	Time 2	8	5	180	
С		Configu	ration mode		9	8.5	210	
					10	10	240	
					11	12	270	
					12	15	300	
					13	20	360	
					14	25	420	
					15	30	480	
					С	40	600	

5.3 Changing setting or application

Description / proce-	Rotary (mode) switch	Rotary knob	System response	LED indi	ications		
dure		(f / t)		RUN		In 2	Out
Factory setting	Position 5	1 Hz	Ready for application	-	-	-	-
Switch operating			Without connected sensors!	Lights up	-	-	-
voltage on							
	Turn to position C		Application is deleted	Lights up	Flashes	Flashes	Flashes
Setting cycle active			Application is deleted	-	-	-	-
Setting cycle active			No valid application saved	Flashes	-	-	-
SRB-E ready for new a	pplications						
Select cut-off frequency		Set frequency		Flashes	-	-	-
or pull-in delay		/ time 1-C					
Select application	Select desired application (1-15).		New application will be loaded	Lights up	-	-	-
	(Time window for setting pro-						
	cedure approx. 3 sec.)						
				Lights up	Lights up	-	-
Setting cycle active				Lights up	Lights up	Lights up	-
				Lights up	Lights up	Lights up	Lights up
Ready for operation	The desired application is configured		Adopt new application	Lights up	-	-	-

6. Diagnostic

6.1 LED indications

LED	Function	Display type
RUN	Ready for operation	Continuously lit
KUN	Not a valid application	Flashes
	Signal on input S12/S22	Continuously lit
In 1/2	Time window for synchronicity exceeded	Flashes quickly
	1-channel opening	Flashes slowly
In 3/4	Input S32 and S42 closed	Continuously lit
111 3/4	1-channel opening	Flashes slowly
	Standstill / time elapsed	Continuously lit
Out 1	Standstill / time elapsed,	Flashes quickly
	input X3 open	
	Safety contacts ON	Continuously lit
	Safety outputs waiting for start	Flashes slowly
Out 2	(input X4)	
	Feedback circuit not closed (input X5)	Flashes slowly
In 1/2	Switch-on delay active	Alternate flashing
Out 1		

Single flashing of all LEDs with mains on

6.2 Malfunctions

Malfunctions and fault causes are displayed with the ERR-LEDs via short and long flashing signals $\,$

150.	-		01 1
LED + Output	Error cause	Long flash	Short flash
	Operating voltage too low	1	1
	Operating voltage too high	1	2
	Invalid rotary switch setting	1	3
	External voltage on output Q1	1	5, 7, 9
	Futomost veltores on autout OO	1	6, 8
	External voltage on output Q2	2	1
	Termination to GND on output Q1	2	2
	Termination to GND on output Q2	2	3
	Cross-wire between inputs S12 and S22	2	4
	Cross-wire between inputs S32 and S42	2	5
	Undefined level on		
ERR	X2	3	4
Y1	X3	3	5
	X7	3	9
	S12	2	9
	S22	3	1
	S32	3	2
	S42	3	3
	Rotary switch > 30 sec. to position C	6	8
	Application changed and activation of operating voltage	RUN, In 1	sh quickly: 1/2, In 3/4, , Out 2
	Application was changed during active operation	In 1/2, In	sh quickly: 3/4, Out 1, ut 2
	Other fault codes: Consult technic Schmersal	al sales dep	t. at

6.3 Warnings standstill monitoring function

Warning messages are indicated by means of short and long flashes on the ERR LED.

LED + Output	Error cause	Long flash	Short flash
	Frequency deviation between the two channels (> 20%)	4	4
EDD	Maximum frequency (6 KHz) reached	4	5
ERR Y1	Limit dropped below, low signal on input S12 and S22 (see 10.1)	4	6
	Standstill signal static or sensor faulty	4	7

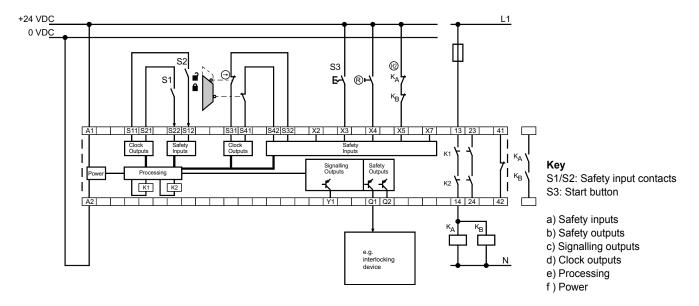
Input X2, delete warning messages

All warning messages that have occurred due to asynchronous signals can be cleared by pressing the Reset button.

7. Wiring examples

7.1 Application example fail-safe delay timer

Two-channel operation with Start function



Function description of actuation:

- Upon actuation of inputs S12 and S22 (closing of contacts S1 and S2) the set activation delay timer is started.
- If the contacts S1 or S2 are opened and closed again before the time has elapsed, the time is restarted.
- Once the period has elapsed, the safety outputs with input X3 can be activated.
- If the safety outputs are to be activated automatically when the time has elapsed, input X3 must be switched to + 24 VDC.

Function description of safety outputs:

• It is possible for e.g. a safety guard to be operated with the two delayed safety outputs Q1 / Q2.

Application example with safety guard monitoring

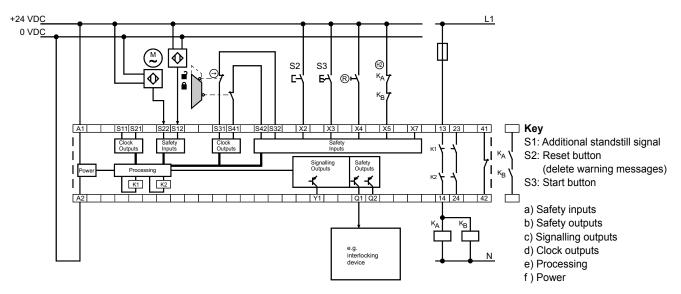
- Two-channel operation of safety guard monitoring with two position switches where one has a positive break contact; with external reset button
- Power level: two-channel operation, suitable for increasing the capacity or number of contacts by means of contactors or relays with positive
 action contacts and feedback circuit



Signalling outputs must not be used in safety circuits.

7.2 Application examples safe standstill monitoring

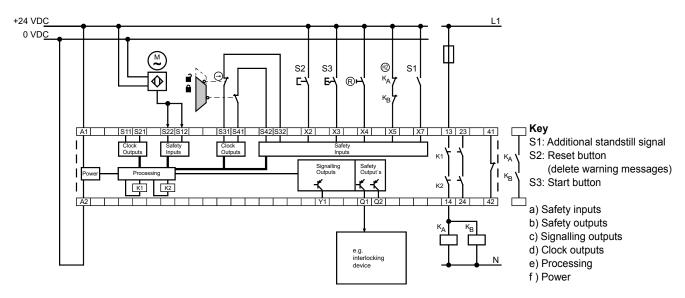
Two-channel operation with level monitoring and Start function



Function description with level monitoring:

- The inputs S12 and S22 monitor the pulses from the sensors connected and compare them with the cut-off frequency set.
- The frequencies from the two sensors are continuously compared. A difference > 20% is detected as an error!
- After dropping below the cut-off frequency the safety output can be activated using input X3.
- If the safety outputs are to be activated automatically, the input X3 must be connected to + 24 VDC.

Two-channel operation with additional standstill signal and Start function



Function description with additional standstill signal:

- The inputs S12 and S22 monitor the pulses from the sensor connected and compare them to the cut-off frequency set.
- The input X7 monitors the standstill signal function as a function of the frequency from the sensor. A difference > 5 s is detected as an error!
- After dropping below the cut-off frequency and standstill signal (= 1), the safety outputs can be activated using input X3.
- If the safety outputs are to be activated automatically, the input X3 must be connected to + 24 VDC.

Function description of safety outputs:

 \bullet It is possible to operate, e.g. a safety guard using the two safety outputs Q1 / Q2.

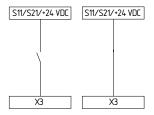
Application examples with safety guard monitoring

- Two-channel operation, shown for safety guard monitoring with two position switches where one has a positive beak contact; with external Reset button
- Power level: two-channel operation, suitable for increasing the capacity or number of contacts by means of contactors or relays with positive action contacts and feedback circuit

7.3 Start configuration, time monitoring / standstill monitoring

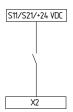
7.3.1 Start/Autostart

- The safety outputs can be activated after the switch-on delay has elapsed or the cut-off frequency has been dropped below.
- With autostart, X3 must be bridged to S11, S21 or +24 VDC



7.3.2 Reset warning message

 All warning messages that have occurred due to asynchronous signals can be deleted by pressing the Reset button. The reset function is triggered on releasing the button.



7.4 Start configuration safety guard monitoring

7.4.1 External reset button

 Manual start or activation of the module occurs when the button is released.



Monitoring of max. actuation time 0.03 sec. ... 3 sec. If the time is exceeded, the module cannot be started!

7.4.2 Reset without monitoring / autostart

- The manual start or the activation of the module occurs when the button is pressed (not when it is released!).
- With autostart, X4 must be bridged to S31, S41 or +24 VDC



Not admitted without additional measure due to the risk of gaining access by stepping behind!



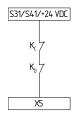
Within the meaning of IEC/EN 60204-1 paragraph 9.2.5.4.2 the operating mode "automatic start" is only restrictedly admissible. In particular, any inadvertent restart of the machine must be prevented by other suitable measures.



Reset button (detection of the trailing edge)	Reset without monitoring / autostart
Rotary knob position	Rotary knob position
1, 2, 5, 6, 8, 9, 12, 13	3, 4, 7, 10, 11, 14, 15

7.4.3 Feedback circuit

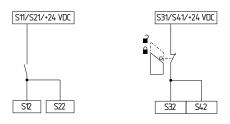
 Suitable for increase in capacity or number of contacts by means of contactors or relays with positive-guided contacts. If the feedback circuit is not required, establish a bridge.



7.5 Sensor configuration

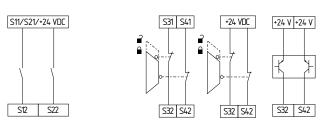
Single channel signal processing

(Category 1 - PL c to ISO 13849-1 possible.



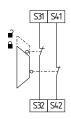
Rotary knob position	Function
9, 11, 13, 15	Safety guard monitoring and time monitoring

Dual channel signal processing without cross-circuit monitoring (Cat. 4 - PL e to ISO 13849-1 only possible with protective wiring)



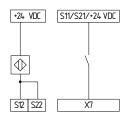
Rotary knob position	Function
9, 11, 13, 15	Safety guard monitoring and time monitoring (S12/S22 < 5s)

Dual channel signal processing with cross-circuit monitoring (Category 4 – PL e to ISO 13849-1 possible)



Rotary knob position	Function
1, 3, 5, 8, 10, 12, 14	Safety guard monitoring

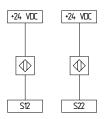
Two-channel signal processing with standstill signal (Category 3 – PL d to ISO 13849-1 possible)



Rotary knob position	Function
5, 6, 7	Standstill monitoring

Two-channel signal processing with level monitoring

(Lay wires to the pulse generators separately and with protection, cat. 4 - PL e according to ISO 13849-1 can be achieved)



Rotary knob position	Function
1, 2, 3, 4	Standstill monitoring

8. Set-up and maintenance

8.1 Commissioning

The safety relay module features protection class IP54 for installation in a switch cabinet.

The safety relay module is delivered ready for operation.

8.2 Functional testing

The safety function of the safety-monitoring module must be tested. The following conditions must be previously checked and met:

- 1. Correct fixing
- 2. Check the integrity of the cable entry and connections
- 3. Check the safety-monitoring module's enclosure for damage.
- Check the electrical function of the connected sensor technology and their influence on the safety-monitoring module and the downstream actuators.

The safety relay module features self-test functions. If a fault is detected, the system adopts a safe mode and leads, if necessary, to undelayed deactivation of all safety outputs.

8.3 Behaviour in the case of faults

In the event of a fault the following procedure is recommended:

- 1. Identify faults according to flash codes from chapter 6.2.
- 2. Rectify the fault if it is described in the table.
- 3. Switch operating voltage off and on and erase fault mode. If fault could not be rectified, please contact the manufacturer.

8.4 Setting report

This report regarding the setting of the device must be completed accordingly by the customer and enclosed in the technical documentation of the machine.

The setting report must be available whenever a safety check is performed.

Company:		
The safety-monit	toring module is used in	the following machine:
Machine n°	Machine type	Module n°
Configured appli	cation (mode):	
Set drop-out dela	ay (t):	
Cut-off frequency	y set (f):	
Set on (date)	Signature of the re	sponsible person

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8.5 Maintenance

A regular visual inspection and functional test, including the following steps, is recommended:

- 1. Check the correct fixing of the safety-monitoring module
- 2. Check the cable for damages
- 3. Check electrical function



If a manual functional check is necessary to detect a possible accumulation of faults, then this must take place during the intervals noted as follows:

- at least every month for PL e with category 3 or category 4 (according to ISO 13849-1) or SIL 3 with HFT (hardware fault tolerance) = 1 (according to IEC 62061);
- at least every 12 months for PL d with category 3 (according to ISO 13849-1) or SIL 2 with HFT (hardware fault tolerance) = 1 (according to IEC 62061).

Damaged or defective components must be replaced.

9. Disassembly and disposal

9.1 Disassembly

The safety control module is only to be removed in a de-energised condition.

9.2 Disposal

The safety control module must be disposed of in an appropriate manner in accordance with the national regulations and laws.

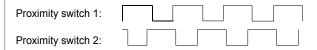
10. Appendix

10.1 Wiring/circuit information

Two-channel signal processing with level monitoring

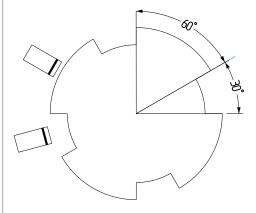
The proximity switches must be attached at a disc cam such at least one proximity switch is always actuated.

This can be realised by a minimum 1:1 division of the disc cam. When the proximity switches are correctly installed, the following unique signal sequence should be obtained by the utilisation of the switching hysteresis of the proximity switches during the rotation of the disc cam.



The adjustment of the proximity switches is facilitated, when the cam has a 2:1 division (or higher).

Example cam



Proximity switches / pulse generators

Use PNP-switching sensors with normally open function.

EU Declaration of conformity

EU Declaration of conformity

9 SCHMERSAL

Original K.A. Schmersal GmbH & Co. KG

Möddinghofe 30 42279 Wuppertal Germany

Internet: www.schmersal.com

We hereby certify that the hereafter described components both in their basic design and construction conform to the applicable European Directives.

Name of the component: SRB-E-402FWS-TS

Type: See ordering code

Description of the component: Fail-safe delay timer, fail-safe standstill monitor and

safety guard monitoring

Relevant Directives: Machinery Directive 2006/42/EC **EMC-Directive** 2014/30/EU

RoHS-Directive 2011/65/EU

Applied standards: ISO 13849-1:2015, ISO 13849-2:2012,

IEC 61508 parts 1-7:2010, IEC 62061:2015

Notified body for the prototype test: TÜV Rheinland Industrie Service GmbH

Alboinstr. 56, 12103 Berlin

ID n°: 0035

EC-prototype test certificate: 01/205/5365.00/18

Person authorised for the compilation

of the technical documentation:

Oliver Wacker Möddinghofe 30 42279 Wuppertal

Place and date of issue: Wuppertal, July 17, 2018

Authorised signature Philip Schmersal Managing Director



SRB-E-402FWS-TS-C-EN

The currently valid declaration of conformity can be downloaded from the internet at www.schmersal.net.





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